Bahria University

Karachi Campus

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LAB EXPERIMENT NO.

**7**

LIST OF TASKS

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| TASK NO | OBJECTIVE |
| 1 | Write a program to generate a PWM signal with duty cycles (25%, 50%, 75% & 100%) |
| 2 | Write a program to interface DC motor with Arduino Uno. |
| 3 | Write a program in Arduino Uno to control the speed of DC motor using PWM. |

Submitted On:

28 December 2023

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(Date: DD/MM/YY)

**Task 1:** Write a program to generate a PWM signal with duty cycles (25%, 50%, 75% & 100%)

**Solution:**

void setup() {

  pinMode(11, OUTPUT);}

void loop() {

  analogWrite(11, 63.75); // 25 % duty cycle delay(200);

  delay(200);

  analogWrite(11, 127);  // 50 % duty cycle

  delay(200);

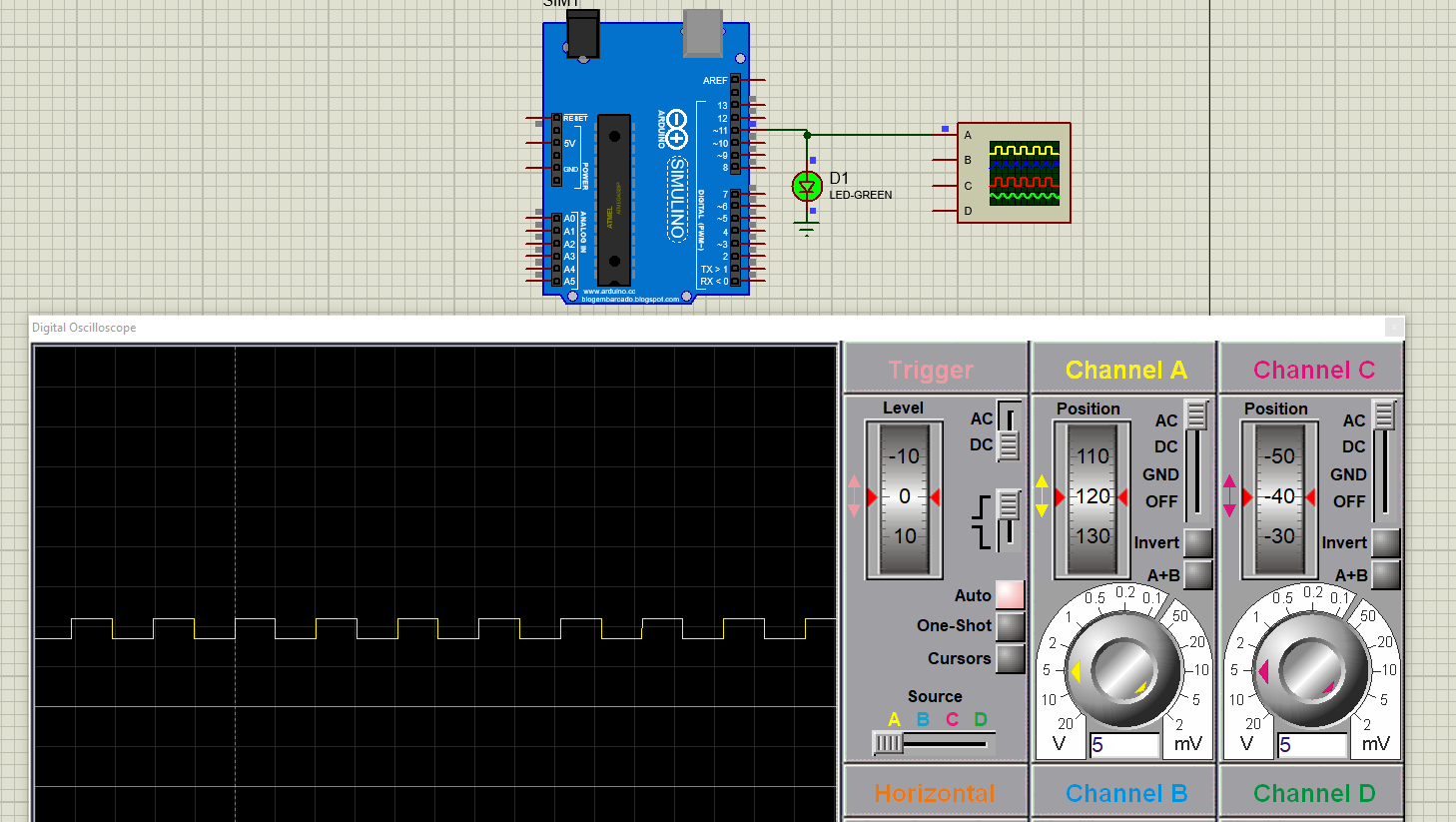
  analogWrite(11, 191);  // 75 % duty cycle

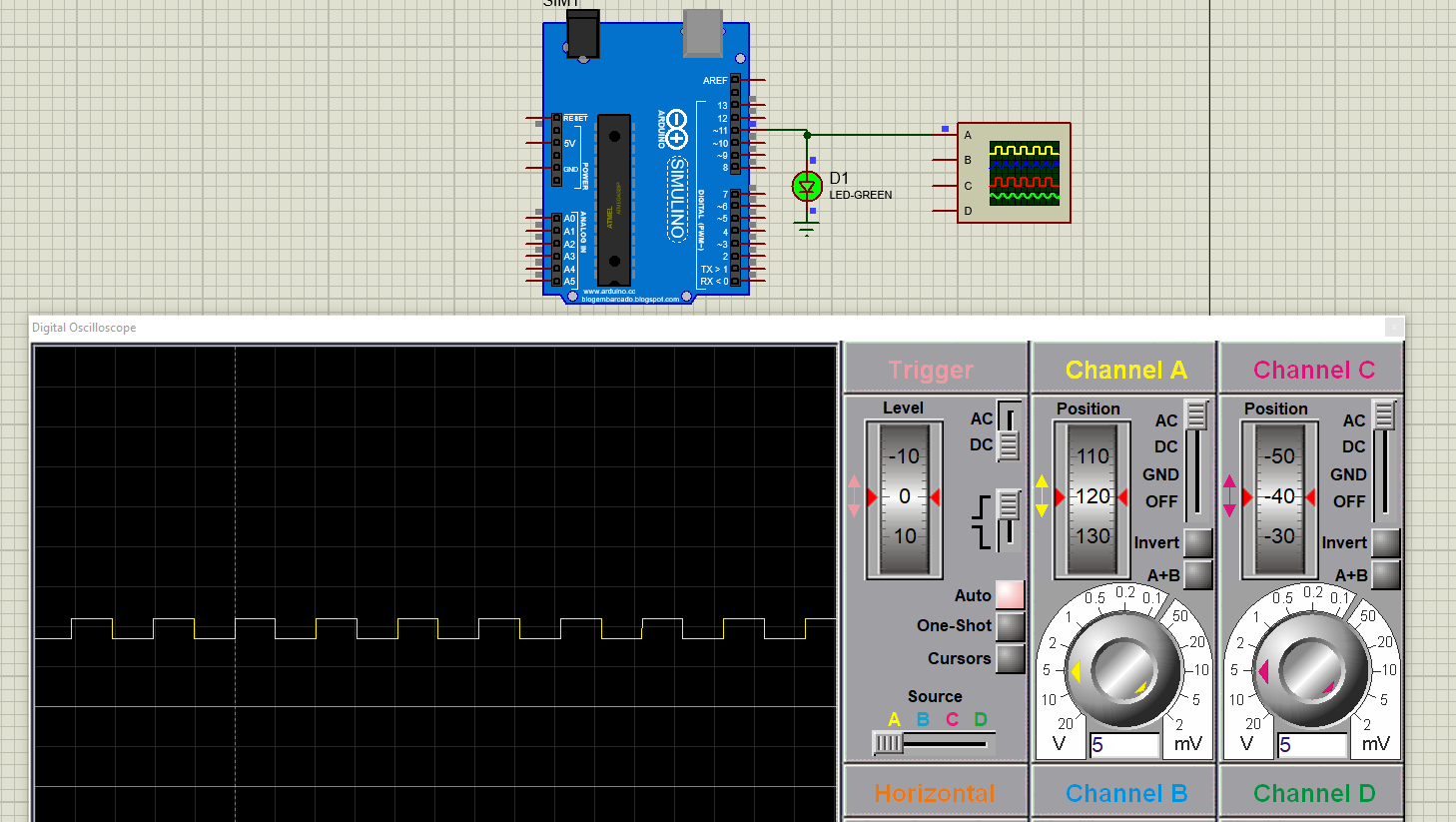
  delay(200);

  analogWrite(11, 255);  // 100 % duty cycle

  delay(200);}

**Output:**

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**Task 2:** Write a program to interface DC motor with Arduino Uno.

**Solution:**

int in1 = 10;

int in2 = 9;

int en = 8;

void setup() {

  pinMode(in1, OUTPUT);

  pinMode(in2, OUTPUT);

  pinMode(en, OUTPUT);}

void loop() {

  digitalWrite(en, HIGH);

  digitalWrite(in1, HIGH);

  digitalWrite(in2, LOW);

  delay(5000);

  digitalWrite(en, LOW);

  delay(1000);

  digitalWrite(en, HIGH);

  digitalWrite(in2, HIGH);

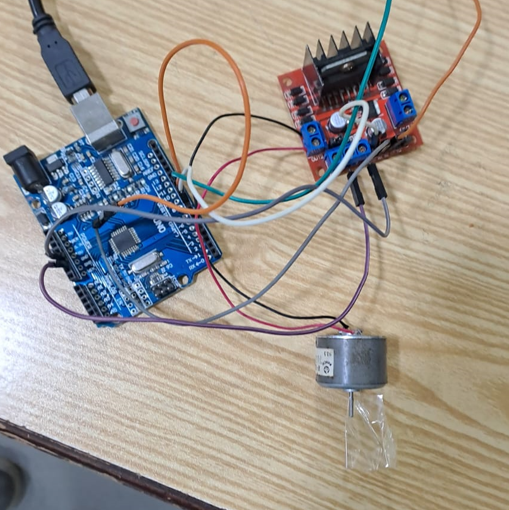
  digitalWrite(in1, LOW);

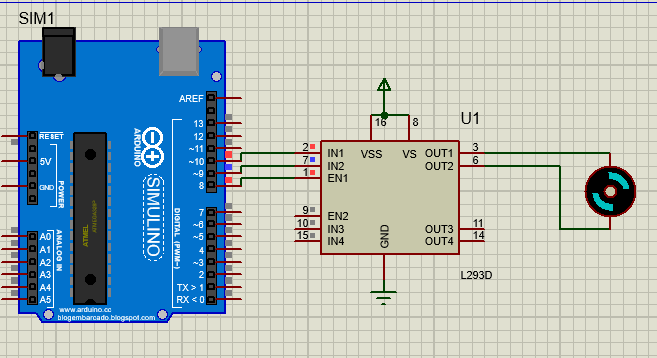
  delay(5000);

  digitalWrite(en, LOW);

  delay(1000);}

**Output:**

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**Task 3:** Write a program in Arduino Uno to control the speed of DC motor using PWM.

**Solution:**

const int Control\_Pin = A0; //Control Pin

const int IN1 = 13;

const int IN2 = 12;

const int ENA = 11;

void setup ()  {

  pinMode(IN1, OUTPUT);  // Set the pin as OUTPUT

  pinMode(IN2, OUTPUT);  // Set the pin as OUTPUT

  pinMode(ENA, OUTPUT);   //PWM Pin}

void loop ()  {

  int Control\_Value = analogRead(Control\_Pin);  // read the input on pin:

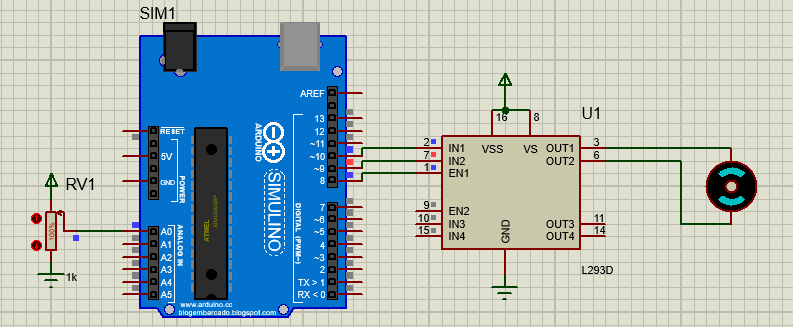
  int Motor\_Speed = map(Control\_Value, 0,1023, 0,255);

  analogWrite(ENA, Motor\_Speed); //PWM Signal to control the speed of motor. (0 - 255)

  digitalWrite(IN1, HIGH);

  digitalWrite(IN2, LOW);}

**Output:**

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